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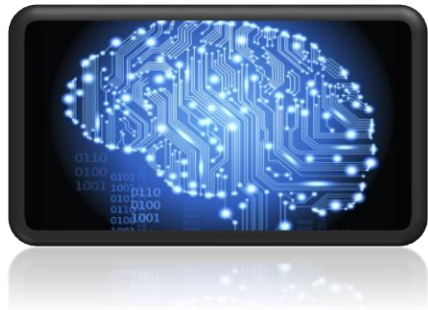
Convolutional Neural Networks on embedded automotive platforms: a qualitative comparison

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Convolutional Neural Networks



✓ Extensively adopted in the embedded world

✓ Computer vision and image processing tasks,
– object categorization and labeling

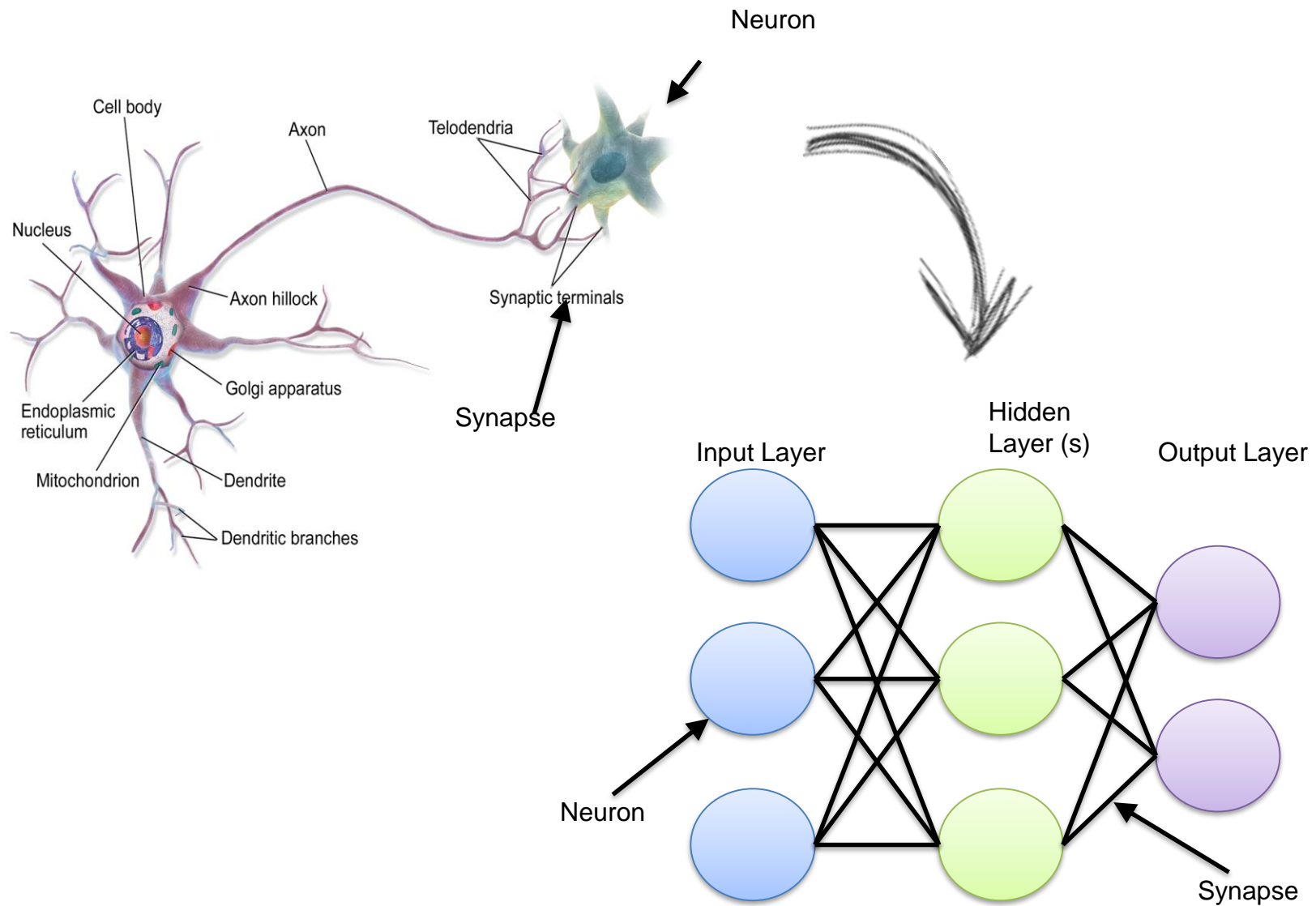


✓ Autonomous driving, industry 4.0.





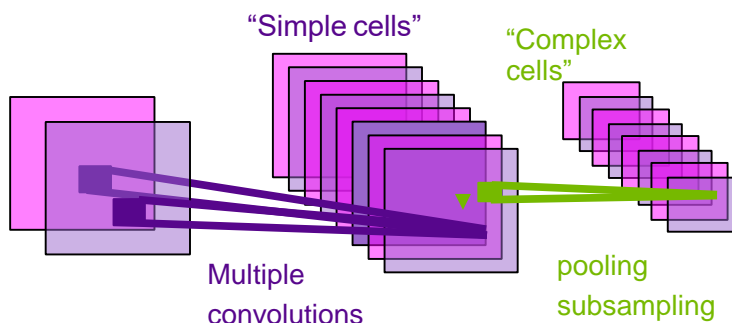
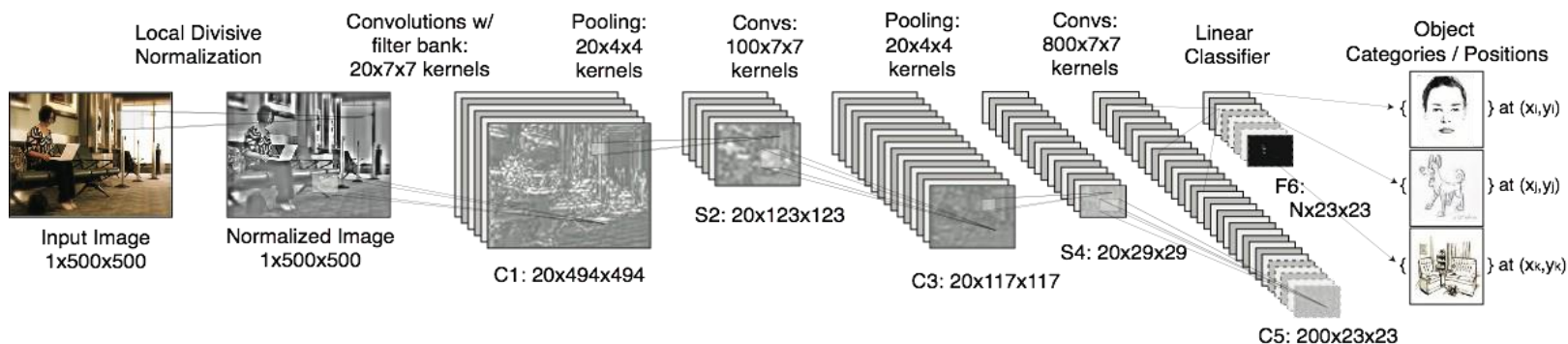
Neural Networks





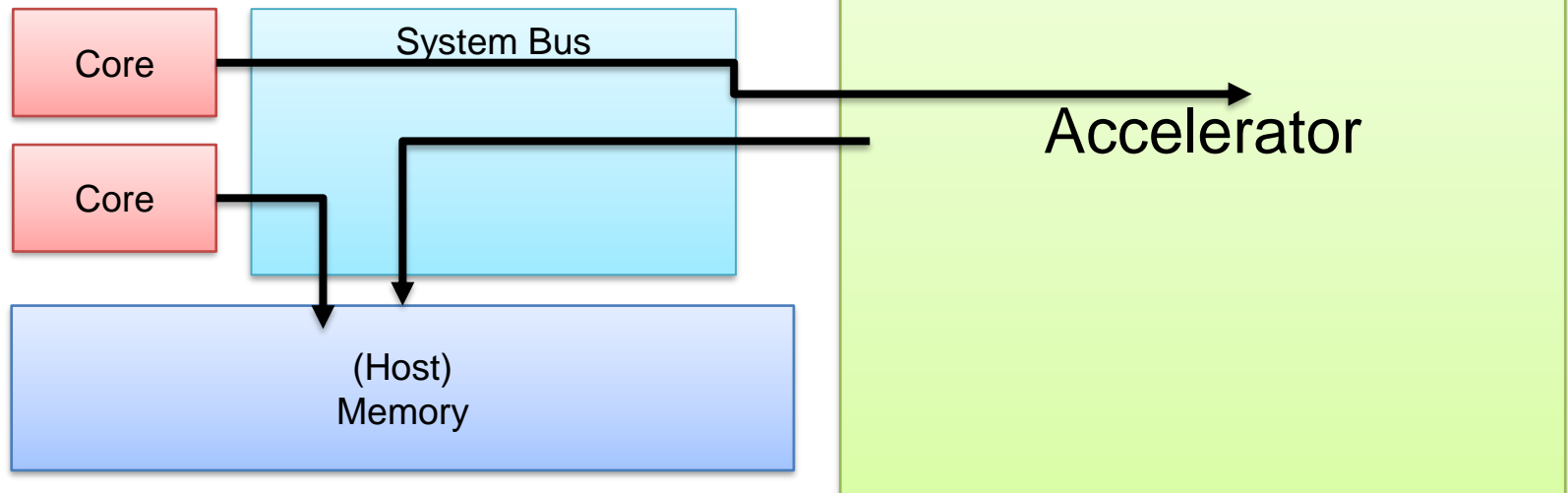
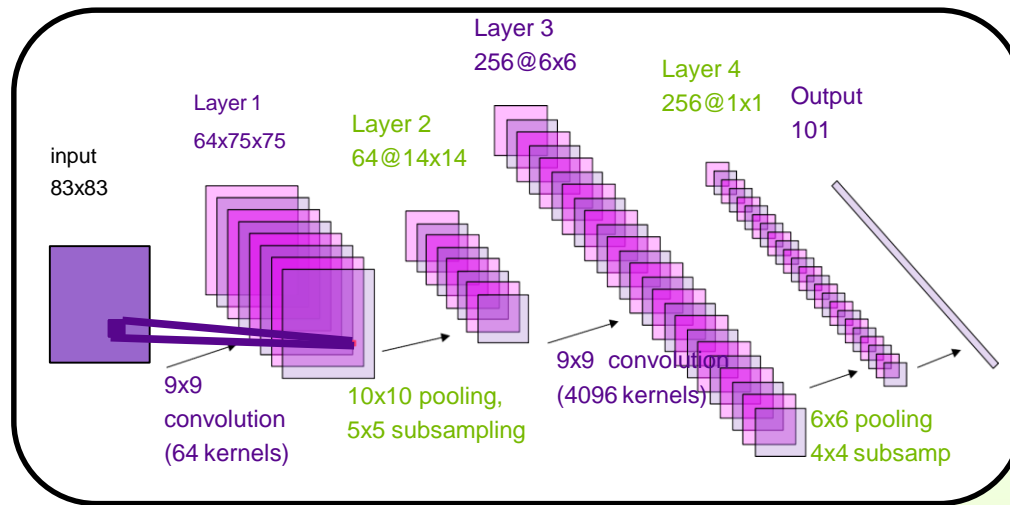
Convolutional Neural Networks

- ✓ Multiple bidimensional layers
- ✓ Huge number of multiply-accumulate (MAC) operation
- ✓ on thousands of pixel of an input image



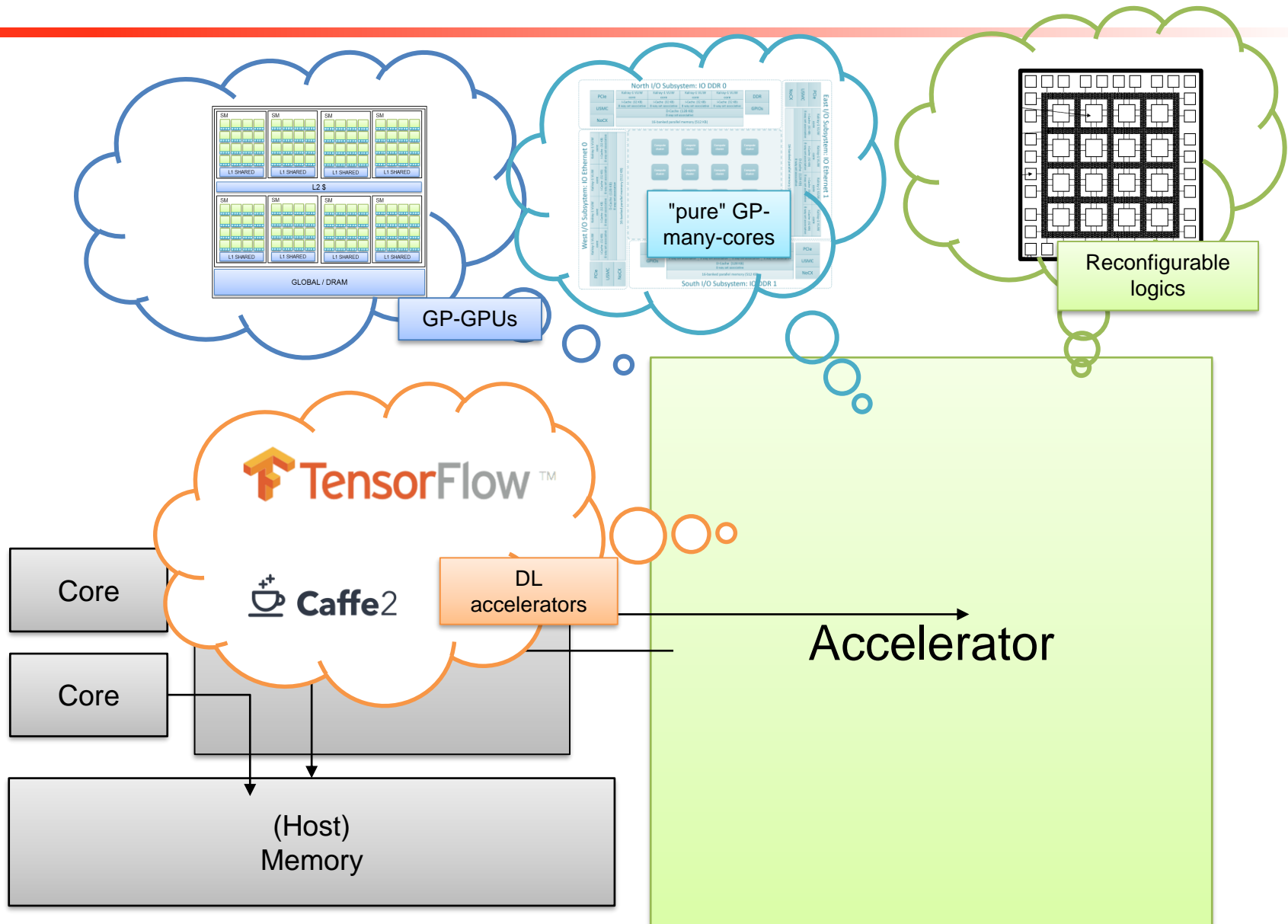


CNN on highly parallel architectures





...which architecture?





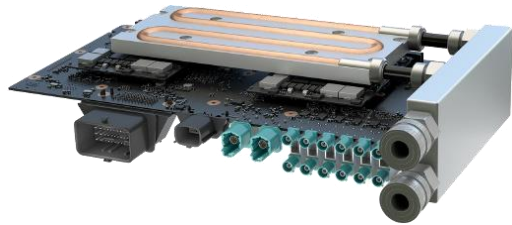
Our aim

Assessing the performance
of representative CNN packages
on state-of-the-art ADAS platforms

- ✓ E2E latency (time per image)
- ✓ Throughput (images per time)
- ✓ Power consumption (Watt)



Current (ongoing) work

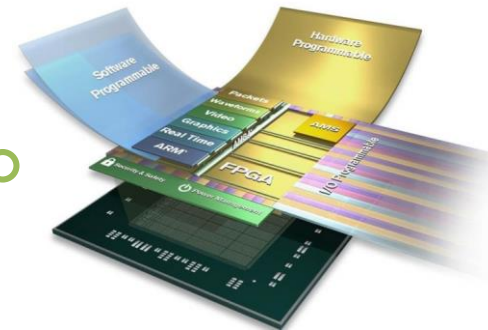


Nvidia Parker SoC

- ✓ Drive PX2 for autonomous driving
- ✓ 4 x ARM Cortex 57 + 2 x Denver
- ✓ Pascal GPU

Xilinx Zynq Ultrascale+

- ✓ 4 x ARM Cortex A53 + 2 x R5
- ✓ Mali GPU
- ✓ FPGA fabric

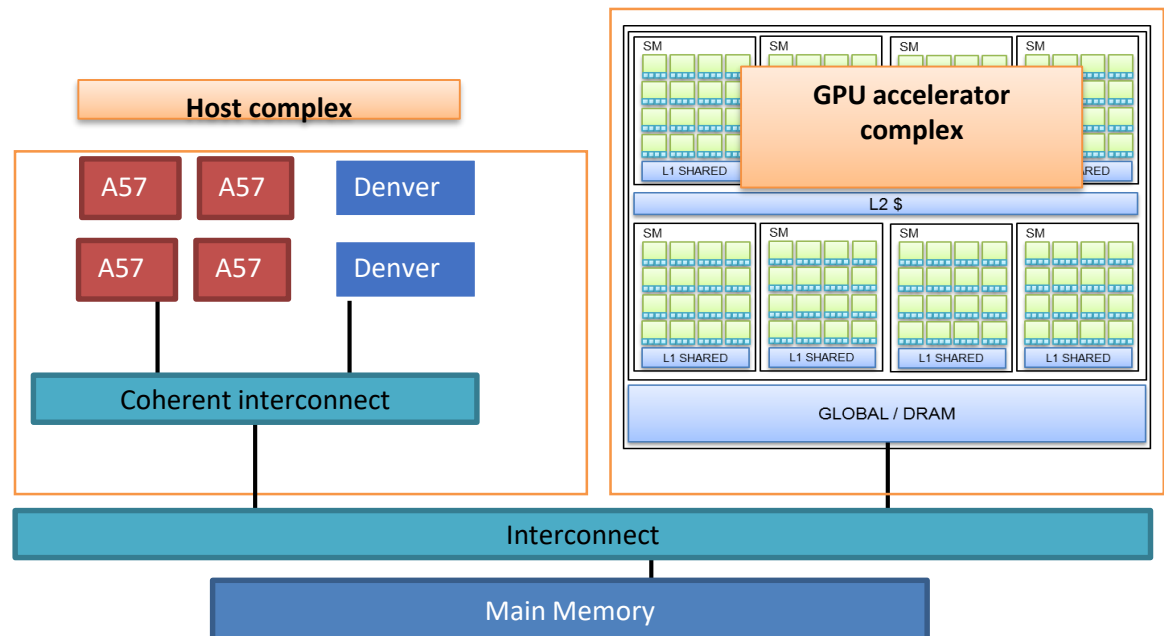




NVIDIA Tegra X2

Embedded computing platform for the automotive market

- ✓ Esa-core host with Big.SUPER configuration
 - 4 ARM A57 + 2 Denver
- ✓ Pascal GPU with 2 NVIDIA Streaming Multiprocessors (SM)
 - 256 CUDA cores. The
- ✓ 1 TFLOP of computing power, @20 Watts.
- ✓ Qualified according to Functional Safety and Road Vehicles Standard
 - ISO 26262's ASIL-B level)
 - marketed as Drive PX2

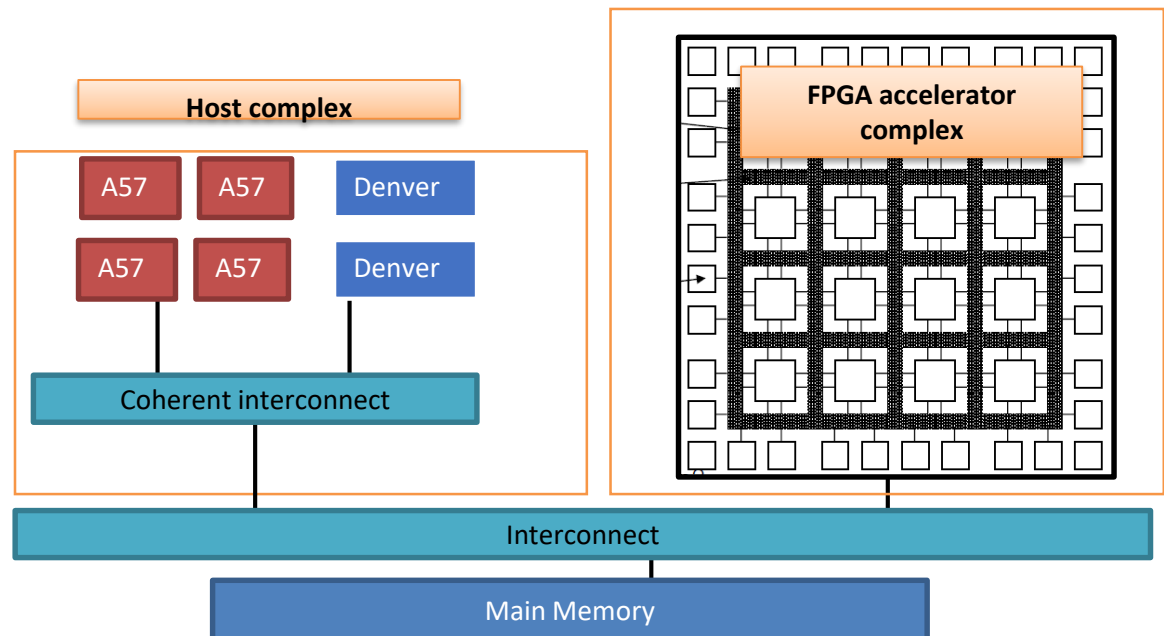




Xilinx Ultrascale+

Embedded computing platform for the automotive market

- ✓ Esa-core host
 - 4 x ARM Cortex A53 + 2 x R5
- ✓ ~~Mali GPU~~
 - Poor programmability (not a GP-GPU)
- ✓ Programmable FPGA fabric





DISCLAIMER





Currently targeted networks

✓ You-only-look-once (Yolo)

– GPU



– FPGA (Darknet)



✓ ZynqNet

– GPU



– FPGA





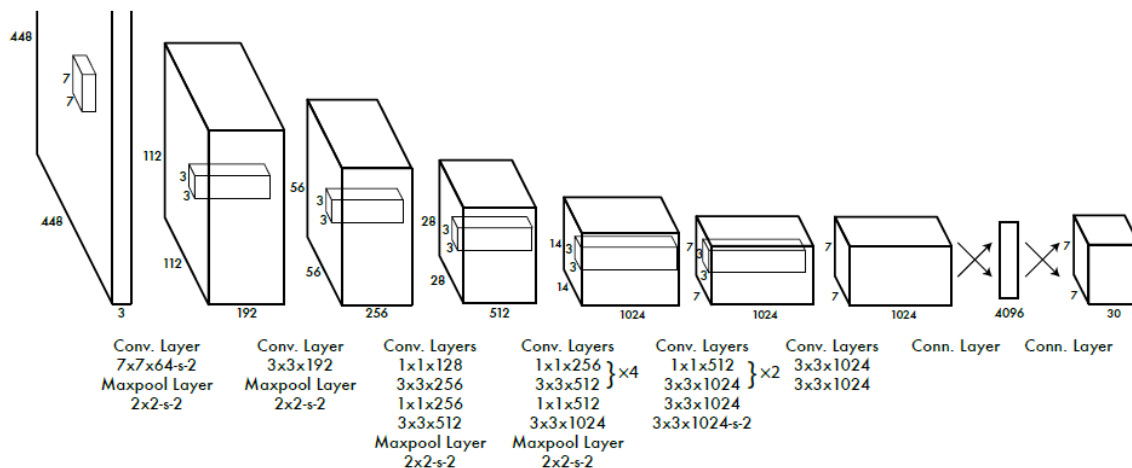
Yolo





"You-only-look-once"

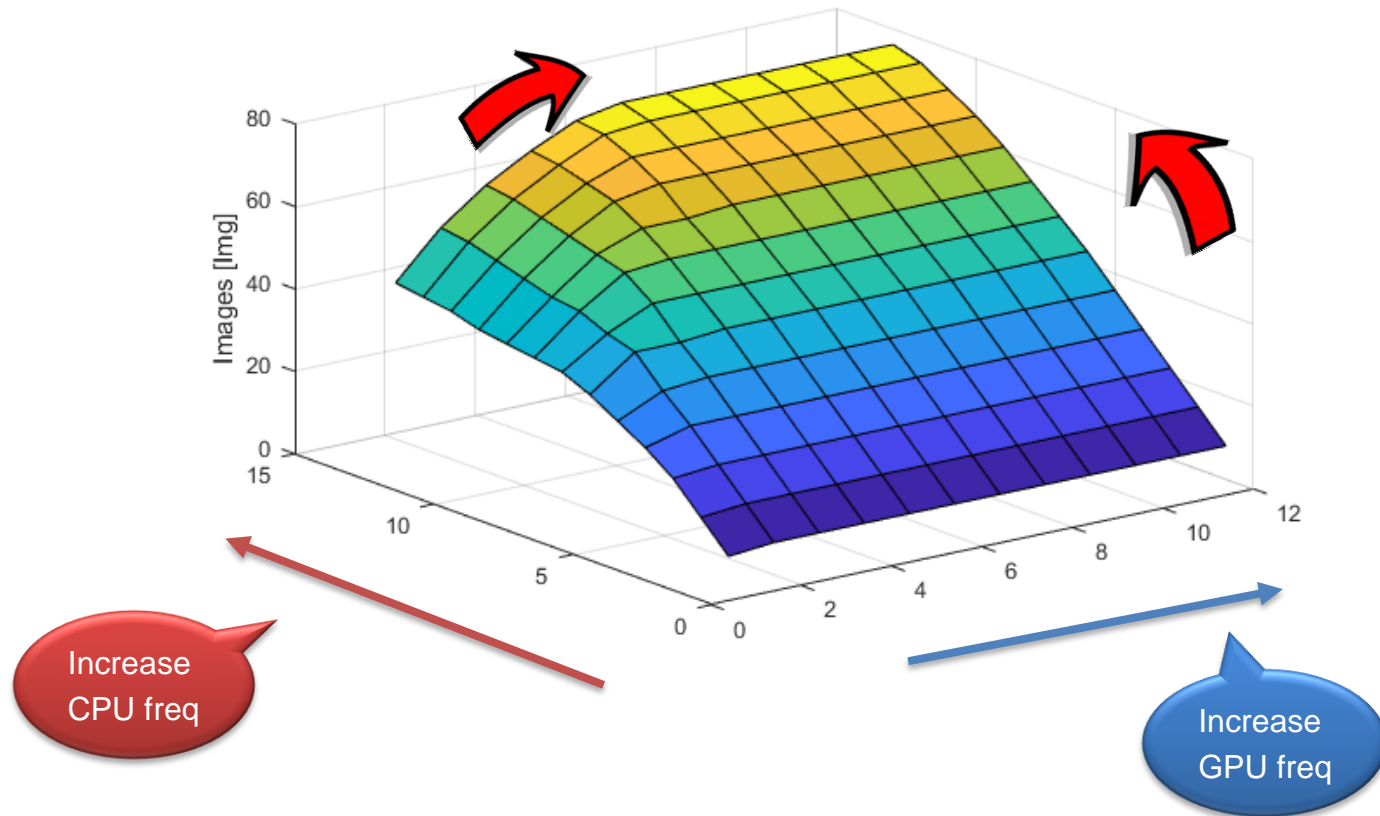
- ✓ 24 convolutional layers followed by 2 fully connected layers
 - Inspired by the GoogleNet project
- ✓ Performs object categorization, detection and segmentation
 - ImageNet dataset, 1k classes
- ✓ FPGA version is based on Darknet (wip)





Yolo on TX2: throughput

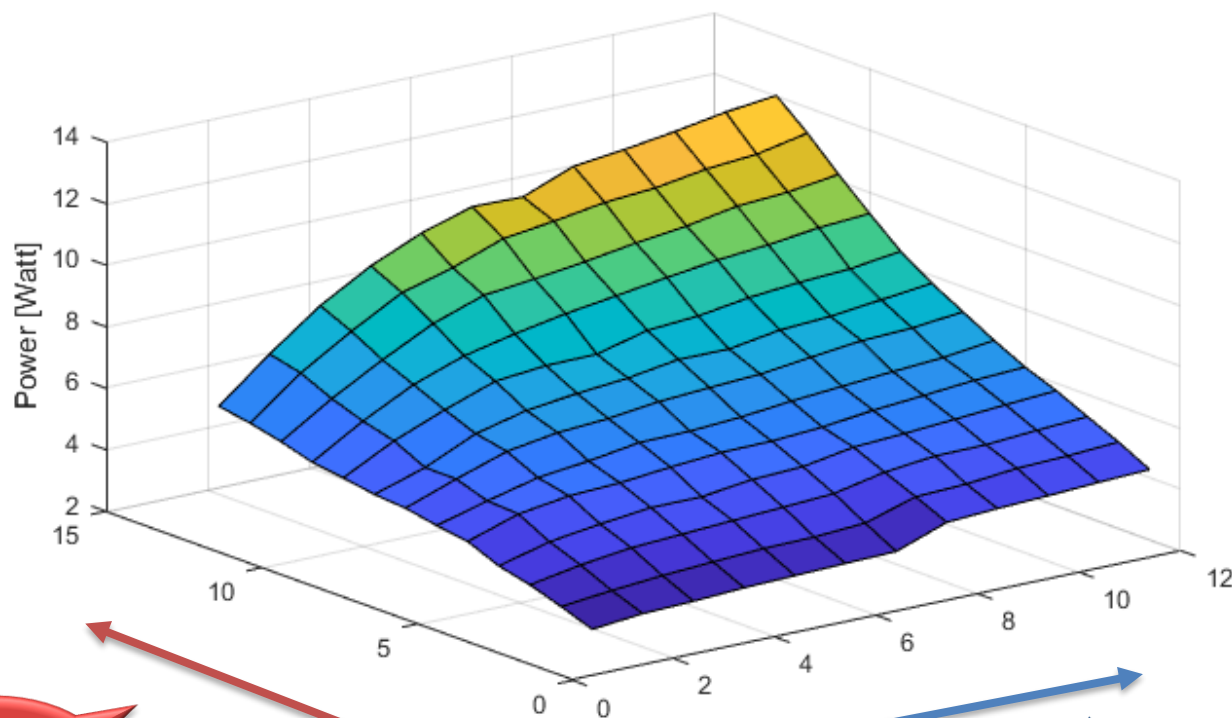
- ✓ Explore CPU/GPU frequency scaling
- ✓ "only" 8 FPS (classification + detection + segmentation)





Yolo on TX2: power consumption

✓ Watt (TX2 claims 20W max)



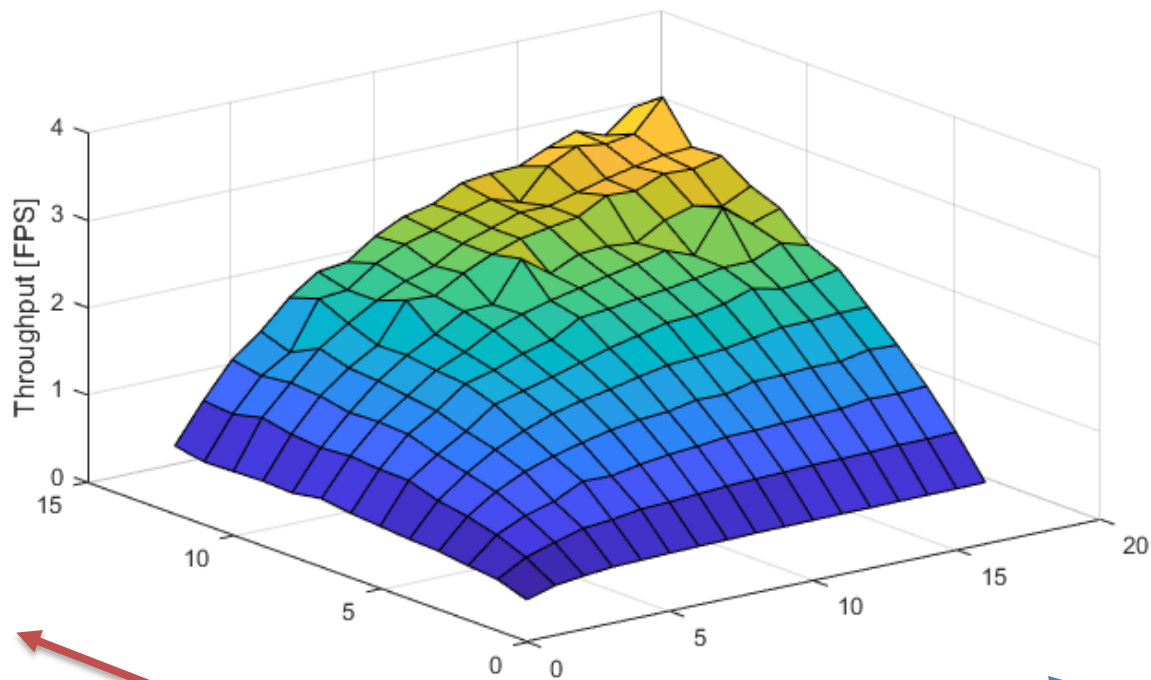
Increase
CPU freq

Increase
GPU freq



Yolo on TX1: throughput

- ✓ Same Host, Maxwell GPU (one generation older)
- ✓ Half perf than TX2



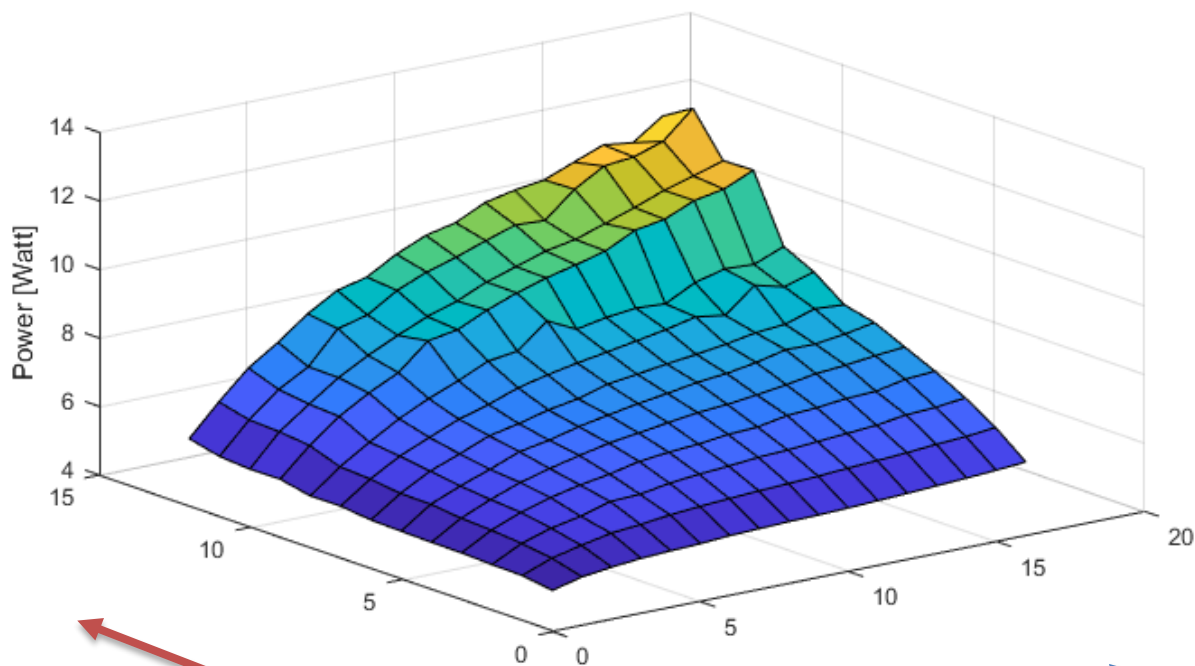
Increase
CPU freq

Increase
GPU freq



Yolo on TX1: power consumption

- ✓ Same power consumption



Increase
CPU freq

Increase
GPU freq



Yolo on XU+

- ✓ Hard to find an equivalent model and to synthesize it on FPGA
- ✓ "We're working for you"





ZynqNet





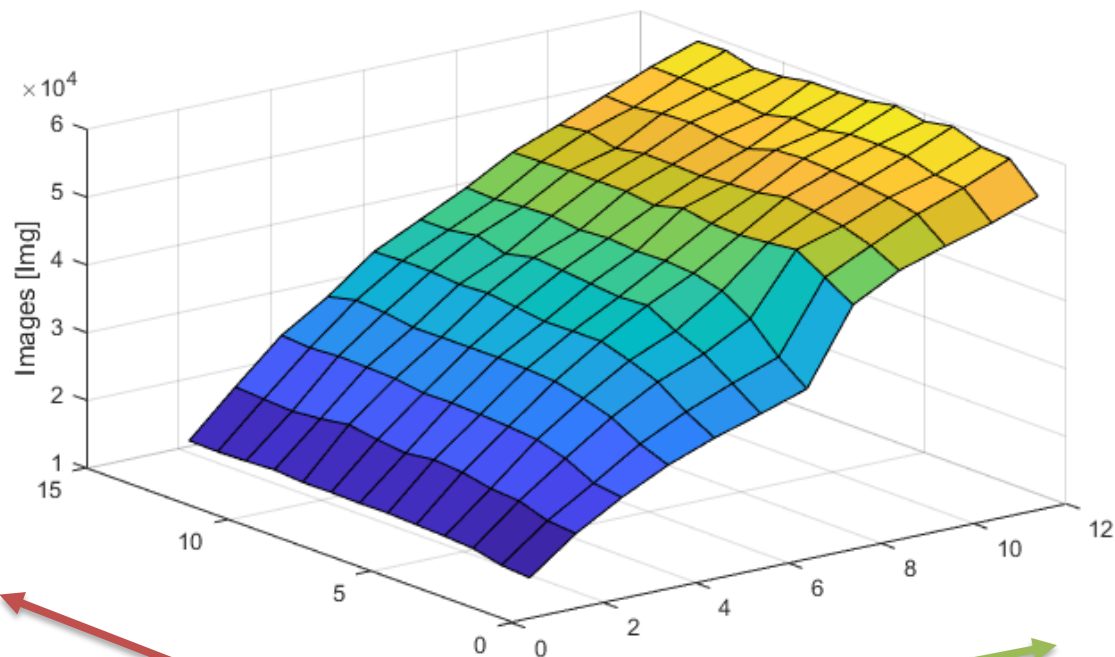
ZynqNet

- ✓ Master thesis of David Gschwend @ETH Zurich
 - <https://github.com/dgschwend/zynqnet>
 - Performs classification
 - ImageNet dataset, 1k classes
- ✓ Written for Zynq arch
 - Not (yet) optimized
 - We ported on XU+
- ✓ Coffee model
 - To get GPU implementation for TX2



ZynqNet on TX2: throughput

- ✓ #images in 5 minutes (...)
- ✓ Up to 200 FPS!!!!

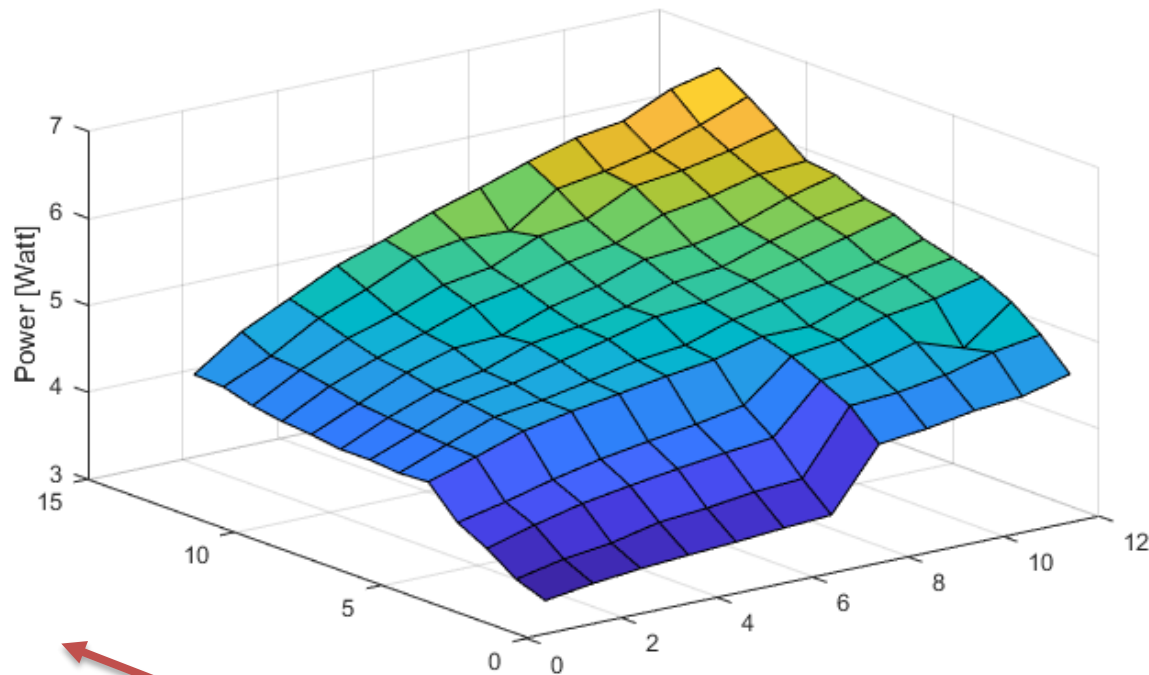


Increase
CPU freq

Increase
GPU freq



ZynqNet on TX2: power consumption

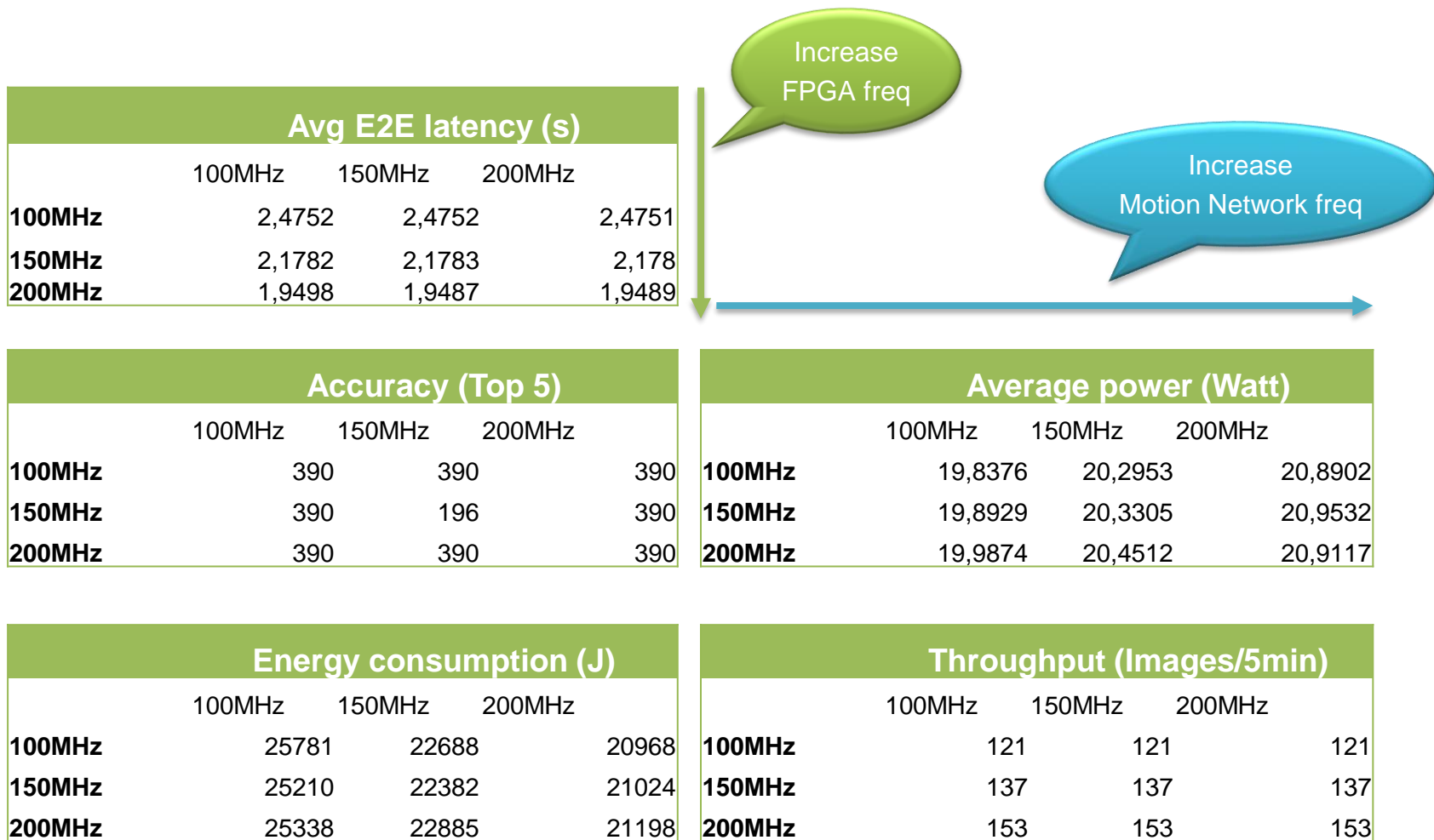


Increase
CPU freq

Increase
GPU freq



ZynqNet on FPGA





What's left?



Future works

- ✓ Yolo
 - ...
- ✓ ZynqNet
 - Optimizing the FPGA code to achieve comparable performance
 - Use fixed point datatypes

Currently, GP-GPU SoCs have **outstanding** performance

- ✓ Other platforms
 - Kalray MPPA -> KaNN Kalray-NN
 - ASIC -> TPU? PoliTo's?
- ✓ Other networks
 - PipeCNN
 - NEURaghe from UniCa/UniBo
 - Our (UniMoRe) CNN that reaches 40FPS @3 channels on ZedBoard



Want to contribute?

- ✓ Are you developing CNN packages for embedded accelerators?
- ✓ Are you developing embedded accelerators?
- ✓ Want to compare?

Join our effort!



Thank you!

*And..see you in Dresden!
(and hopefully Vancouver)*

